

Abstract

a Sub
C2
described

A method is ~~specified~~ for operating an automation system, the automation system having at least one input unit for receiving 5 process signals and at least one output unit for driving external peripherals, which are communicatively interconnected via a bus, ~~the method being characterized in that~~ at least one of the input units and at least one of the output units are constructed as failsafe input unit $\langle EE \rangle$ and failsafe output 10 unit $\langle AE \rangle$, respectively, ~~and that~~ the failsafe input unit $\langle EE \rangle$ transmits a telegram $\langle T \rangle$ to the failsafe output unit $\langle AE \rangle$ at predetermined times, ~~and that the telegram~~ $\langle T \rangle$ includes at least one useful information item $\langle TN \rangle$, one destination point code $\langle TT \rangle$ designating the addressed output unit $\langle AE \rangle$ and one 15 origin code $\langle TS \rangle$ designating the transmitting input unit $\langle EE \rangle$, and that the output unit $\langle AE \rangle$ interprets the continuous reception of the telegram $\langle T \rangle$ as an indication of an intact communication relationship, and otherwise shifts the connected peripherals into a safe state.

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Figure 1

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